X BLADE.

Instruction Manual Bedienungsanleitung Manuel d'utilisation Manuale di Istruzioni



NOTICE

All instructions, warranties and other collateral documents are subject to change at the sole discretion of Horizon Hobby, LLC. For up-to-date product literature, visit horizonhobby.com or towerhobbies.com and click on the support or resources tab for this product.

Meaning of Special Language

The following terms are used throughout the product literature to indicate various levels of potential harm when operating this product:

<u>WARNING:</u> Procedures, which if not properly followed, create the probability of property damage, collateral damage, and serious injury OR create a high probability of superficial injury.

CAUTION: Procedures, which if not properly followed, create the probability of physical property damage AND a possibility of serious injury.

NOTICE: Procedures, which if not properly followed, create a possibility of physical property damage AND a little or no possibility of injury.

WARNING: Read the ENTIRE instruction manual to become familiar with the features of the product before operating. Failure to operate the product correctly can result in damage to the product, personal property and cause serious injury.

This is a sophisticated hobby product. It must be operated with caution and common sense and requires some basic mechanical ability. Failure to operate this Product in a safe and responsible manner could result in injury or damage to the product or other property. This product is not intended for use by children without direct adult supervision. Do not use with incompatible components or alter this product in any way outside of the instructions provided by Horizon Hobby, LLC. This manual contains instructions for safety, operation and maintenance. It is essential to read and follow all the instructions and warnings in the manual, prior to assembly, setup or use, in order to operate correctly and avoid damage or serious injury.

WARNING AGAINST COUNTERFEIT PRODUCTS: If you ever need to replace a Spektrum™ component found in a Horizon Hobby product, always purchase from Horizon Hobby, LLC or a Horizon Hobby authorized dealer to ensure authentic high-quality Spektrum product. Horizon Hobby, LLC disclaims all support and warranty with regards, but not limited to, compatibility and performance of counterfeit products or products claiming compatibility with DSM® or Spektrum technology.

Age Recommendation: Not for children under 14 years. This is not a toy.

Safety Precautions and Warnings

As the user of this product, you are solely responsible for operating in a manner that does not endanger yourself and others or result in damage to the product or the property of others.

- Always keep a safe distance in all directions around your model to avoid collisions or injury. This model is controlled by a radio signal subject to interference from many sources outside your control. Interference can cause momentary loss of control.
- Always operate your model in open spaces away from full-size vehicles, traffic and people.
- Always carefully follow the directions and warnings for this and any optional support equipment (chargers, rechargeable battery packs, etc.).
- Always keep all chemicals, small parts and anything electrical out of the reach of children.
- Always avoid water exposure to all equipment not specifically designed and protected for this purpose.
 Moisture causes damage to electronics.

- Never place any portion of the model in your mouth as it could cause serious injury or even death.
- Never operate your model with low transmitter batteries.
- Always keep aircraft in sight and under control.
- Always move the throttle fully down at rotor strike.
- Always use fully charged batteries.
- Always keep transmitter powered on while aircraft is powered.
- Always remove batteries before disassembly.
- Always keep moving parts clean.
- · Always keep parts dry.
- · Always let parts cool after use before touching.
- Always remove batteries after use.
- Never operate aircraft with damaged wiring.
- Never touch moving parts.

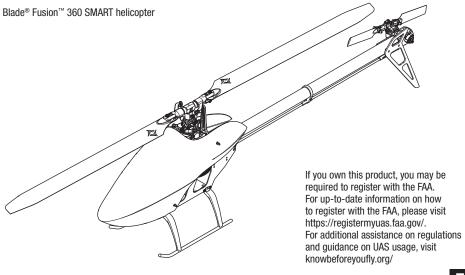
Table of Contents

| Box Contents3 | Tail Belt Tension10 |
|---|---|
| First Flight Preparation4 | Post-Flight Inspections and Maintenance11 |
| Flying Checklist4 | Advanced Tuning (Forward Programming)11 |
| LED Indicator on Flight Controller4 | Advanced Tuning (Non-Forward Programming)12 |
| SMART Throttle4 | Flight Mode and Rate Selection13 |
| Low Voltage Cutoff (LVC)4 | Troubleshooting Guide14 |
| Electronic Speed Controller Governor Operation5 | Exploded View15 |
| Transmitter Setup5 | Parts List |
| Installing the Flight Battery7 | Recommended Parts List |
| Transmitter and Receiver Binding7 | Optional Parts List17 |
| Throttle Hold8 | Limited Warranty18 |
| Control Tests8 | Warranty and Service Contact Information19 |
| Panic Recovery9 | FCC Information |
| Pre-Flight Checklist9 | IC Information19 |
| Flying the Blade Fusion 360 SMART10 | Compliance Information for the European Union20 |
| Gyro Gain Adjustment10 | |
| | |

| Specifications | | | | |
|----------------|-----------------|--|---------------------|-----------------|
| Length | 26.9 in (685mm) | | Main Rotor Diameter | 31.3 in (796mm) |
| Height | 26.9 in (190mm) | | Tail Rotor Diameter | 6.9 in (175mm) |
| Flying Weight | 32.2 oz (915 g) | | | |

| | Components | BNF Basic |
|--------------|--|-----------|
| Airframe | Blade® Fusion 360 SMART | Included |
| Motors | Brushless Motor (BLH5051) | Installed |
| Receiver | Flight Controller/Receiver (SPMFC6250HX, SPM4651T) | Installed |
| ESC | Avian 45Amp Brushless SMART ESC 6S (SPMXAE1045) | Installed |
| Swash Servos | Sub-Micro Digital Heli Cyclic MG Servo (SPMSH3055) | Installed |
| Tail Servo | Sub-Micro Digital Heli Tail MG Servo (SPMSH3065) | Installed |
| Battery | Spektrum™ 2200mAh 3S 11.1V SMART 50C; IC3 (SPMX22003S50) | Required |
| Charger | Li-Po Balancing Charger | Required |
| Transmitter | Full Range DSM2®/DSMX® technology transmitter | Required |

Box Contents



First Flight Preparation

- Remove and inspect contents
- . Begin charging the flight battery (not included)
- Install the flight battery in the helicopter (once it has been fully charged)
- Program your computer transmitter
- · Bind your transmitter
- Familiarize yourself with the controls
- Find a suitable area for flying

Flying Checklist

- □ Always turn the transmitter on first
- Plug the flight battery into the lead from the ESC
- ☐ Allow the ESC to initialize and arm properly
- Verify control directions and gyro compensations are correct
- ☐ Fly the model
- ☐ Land the model
- ☐ Unplug the flight battery from the ESC
- Always turn the transmitter off last

LED Indicator on Flight Controller

| LED Indicator on FC | Indicator Description | |
|-----------------------------------|--|--|
| Slow Green Flash | Ready to Fly | |
| Slow Red Flash | Failsafe Active | |
| Slow Blue Flash | Forward Programming Mode | |
| Yellow Flash (during calibration) | Calibration proceeding normally | |
| Red Flash (during calibration) | Calibration Error, FC not level or is being moved during calibration | |

SMART Throttle

The new line of Spektrum ESCs feature a telemetry function called SMART Throttle. SMART Throttle technology combines the throttle signal with telemetry data from the ESC on one normal three wire servo connector. SMART Throttle ESCs can send current, voltage, ESC temp, and mAh consumed. SMART Throttle telemetry data shows up on your transmitter like any other telemetry sensor. For SMART Throttle to function you must have a SMART Throttle ESC paired with a SMART Throttle telemetry receiver, and a Spektrum DSMX transmitter with telemetry. Only certain Spektrum products include SMART technology compatibility, check your receiver and ESC manual for more information. An update for your transmitter may be required for SMART features. (See www.spektrumrc.com to register and update your transmitter.)

To activate SMART Telemetry:

- 1. Keep the vehicle powered on after binding the transmitter to the receiver
- 2. Scroll to the Telemetry screen
- 3. Scroll to Settings
- 4. Select Auto Config

To activate Speed infomation using SMART Telemetry:

- After doing the initial SMART telemetry configuration keep the vehicle powered on
- 2. Scroll to the Telemetry screen
- 3. Scroll to SMART ESC and double select
- 4. Scroll down to NEXT
- Enter the values for the magnetic pole count of the motor and the gear ratio (motor and gear ratio information can be found in the manual for your vehicle)

When the radio is on and connected to a receiver sending SMART Data, the SMART Logo will appear under the battery logo on the home page and a signal bar will appear in the top left corner of the screen. Scrolling down, past the servo monitor, the SMART screens will appear. Select either ESC, battery, or both for display to suit your preference.

Low Voltage Cutoff (LVC)

The ESC will continuously lower power to the motor until complete shutdown when the battery reaches 12V under load. This helps prevent over-discharge of the Li-Po battery. Land immediately when the ESC activates LVC. Continuing to fly after LVC can damage the battery, cause a crash or both. Crash damage and battery damaged due to over-discharge are not covered under warranty.

Repeatedly flying the helicopter until LVC activates will damage the helicopter battery.

Disconnect and remove the Li-Po battery from the aircraft after use to prevent trickle discharge. During storage, make sure the battery charge does not fall below 3V per cell.

Electronic Speed Controller Governor Operation

The included electronic speed controller (ESC) utilizes a head speed governor to maintain a constant head speed during flight. The governor will work to maintain a constant head speed throughout maneuvers and the discharge cycle of the flight battery.

The throttle position determines the requested head speed, and although throttle curves are still used, they will be a constant value; all positions of the curve are set to the same value. The lowest position of the normal flight mode throttle curve must be set to 0 to ensure the motor can be disabled.

The default throttle curve settings listed in the transmitter setup tables should be acceptable to most pilots and we recommend starting with these values. If you feel an adjustment is necessary after a few flights, adjust the throttle percentage for the desired flight mode. We recommend making small changes of 5% to find your preferred head speed.

Remember the throttle position on the transmitter is simply requesting a specific head speed and this is not related to the actual motor power percentage.

Transmitter Setup

Program your transmitter before attempting to bind or fly the helicopter. Always start by creating a new model in the transmitter to ensure no existing settings are inadvertently used. Transmitter programming values are shown below for the Spektrum transmitters. The files for models using Spektrum transmitters with Spektrum AirWare™ software are also available for download online at www.spektrumrc.com.

DX7s, DX8

| SYSTEM SETUP | | | |
|--------------|--------|--|--|
| Model Type | | | |
| HELI | | | |
| Swash Type | | | |
| 1 servo N | ormal | | |
| F-Mode Setup | | | |
| Flight Mode | F Mode | | |
| Hold | Hold | | |
| SW Select | | | |
| Trainer | AUX 2 | | |
| F Mode | Gear | | |
| Gyro | INH | | |
| Mix | INH | | |
| Hold | INH | | |
| Knob INH | | | |
| Frame Rate | | | |
| 11ms | | | |
| DSMX | | | |
| | | | |

| FUNCTION LIST | | | | | | |
|---------------|--------------|-----------------------|------|-----|------|-------|
| Servo S | Setup | | | | | |
| Channe | el | Ti | rave | el | Rev | erse/ |
| All Chann | els | 10 | 0/1 | 00 | No | rmal |
| D/R & E | хро | | | | | |
| | | vitch Pos Ail D/R) | | | | |
| Chan | DX7s | D | X8 | D, | /R | Ехро |
| AILE/ | 0 | | 0 | 100 | /100 | 0 |
| ELEV/ | | | 1 | 85 | /85 | 0 |
| RUDD | 1 | 2 | 2 | 85 | /85 | 0 |
| Gyro | | | | | | |
| No | rmal | | | 7 | 75% | |
| Stu | ınt 1 | | | 7 | 75% | |
| Н | old | | | 7 | 75% | |
| Cha | Channel Gear | | | | | |
| S | SW F Mode | | | | ; | |
| | | | | | | |

| | Throttle Curve | | | | | | |
|---|----------------|------------|--------------|------|------|------|------|
| | Switch Pos | s (F Mode) | | | | | |
| | DX7s | DX8 | Pt 1 | Pt 2 | Pt 3 | Pt 4 | Pt 5 |
| | N | N | 0 | 65 | 65 | 65 | 65 |
| | | 1 | 80 | 80 | 80 | 80 | 80 |
| ٦ | 1 | 2 | 100 | 100 | 100 | 100 | 100 |
| | HOLD | HOLD | 0 | 0 | 0 | 0 | 0 |
|) | Pitch Curv | | | | | | |
| 4 | Switch Pos | s (F Mode) | | | | | |
| 4 | DX7s | DX8 | Pt 1 | Pt 2 | Pt 3 | Pt 4 | Pt 5 |
| ┥ | N | N | 30 | 40 | 50 | 75 | 100 |
| | | 1 | 0 | 25 | 50 | 75 | 100 |
| | 1 | 2 | 0 | 25 | 50 | 75 | 100 |
| 4 | HOLD | HOLD | 0 | 25 | 50 | 75 | 100 |
| 4 | Timer | | | | | | |
| + | Mo | | Count Down | | | | |
| ╛ | Tin | | 3:00 Tone | | | | |
| | Sta | ırt | Throttle Out | | | | |

Over

DX6G2, DX6e, DX7G2, DX8G2, DX8e, DX9, DX18, DX20, NX6, NX8, NX10, iX12, iX20

| SYSTEM SETUP | | | | | |
|--------------------|-------------------|-----|--|--|--|
| Model Type | Model Type HELI | | | | |
| Swash Type | Nor | mal | | | |
| F-Mode Setu | F-Mode Setup | | | | |
| Switch 1 | Switch 1 Switch B | | | | |
| Switch 2 | witch 2 Inhibit | | | | |
| Hold Switch | itch Switch H | | | | |
| | 0 | 1 | | | |

| Channel Assign | | |
|----------------|--|--|
| t Config | | |
| | | |
| | | |
| | | |
| | | |
| Flight Mode | | |
| | | |
| | | |
| Frame Rate | | |
| | | |

^{*} Function is not available on all transmitters

11ms*

| FUNCTION LIST | | | | | |
|---------------|-------------|---------|--|--|--|
| Servo Set | Servo Setup | | | | |
| Channel | Travel | Reverse | | | |
| THR | 100/100 | Normal | | | |
| AIL | 100/100 | Normal | | | |
| ELE | 100/100 | Normal | | | |
| RUD | 100/100 | Normal | | | |
| GER | 100/100 | Normal | | | |

| D/R & Expo | | | | |
|-------------|------------|----------|--------|--|
| Chan | Sw (F) Pos | D/R | Expo | |
| | 0 | 100/100 | 0 | |
| AILE | 1 | 85/85 | 0 | |
| | 2 | 85/85 | 0 | |
| | 0 | 100/100 | 0 | |
| ELEV | 1 | 85/85 | 0 | |
| | 2 | 85/85 | 0 | |
| | 0 | 100/100 | 0 | |
| Rudd | 1 | 85/85 | 0 | |
| | 2 | 85/85 | 0 | |
| Gyro | | | | |
| N | lormal | 75% | , D | |
| S | tunt 1 | 75% | | |
| S | tunt 2 | 75% | | |
| Hold | | 75% | | |
| Channel | | AX2 | | |
| Switch Flig | | Flight N | lode | |

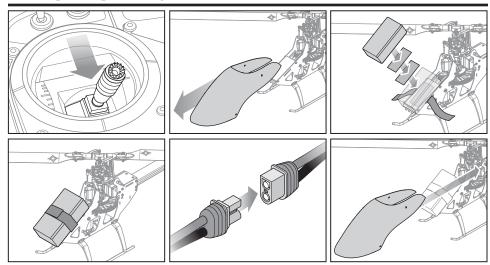
| Mixing | | | |
|---------|----------|--------|-------|
| P-Mix 1 | Normal | | |
| | Channels | -l-> | Ger |
| | Rate | 0/-125 | |
| | Offset | 100 | |
| | Switch | Swi | tch I |
| | Position | 0 | 1 |

| Channel | Travel | Reverse |
|---------|---------|---------|
| PIT | 100/100 | Normal |
| AX2* | 100/100 | Normal |
| AX3* | 100/100 | Normal |
| AX4* | 100/100 | Normal |

| Throt | tle Curve |) | | | |
|--------------|-------------|------|------|------|------|
| Sw P | os | | | | |
| (B) | Pt 1 | Pt 2 | Pt 3 | Pt 4 | Pt 5 |
| N | 0 | 65 | 65 | 65 | 65 |
| 1 | 80 | 80 | 80 | 80 | 80 |
| 2 | 100 | 100 | 100 | 100 | 100 |
| Hol | d 0 | 0 | 0 | 0 | 0 |
| Pitch | Pitch Curve | | | | |
| Sw P | os | | | | |
| (B) | Pt 1 | Pt 2 | Pt 3 | Pt 4 | Pt 5 |
| N | 25 | 37 | 50 | 75 | 100 |
| 1 | 0 | 25 | 50 | 75 | 100 |
| 2 | 0 | 25 | 50 | 75 | 100 |
| HOL | D 25 | 37 | 50 | 75 | 100 |
| | | | | | |

| HOLD | 25 | 37 | 50 | 75 | 100 |
|----------|----|----|-------|---------|-----|
| Timer | | | | | |
| Mode | | | Coun | t Dow | /n |
| Time | | | 5 | :00 | |
| Start | | | Throt | ttle Oı | ut |
| Over | | | 5 | 5% | |
| One Time | ; | | Inl | hibit | |

Installing the Flight Battery



- 1. Lower the throttle.
- 2. Power on the transmitter.
- 3. Center all trims.
- To allow the ESC to arm and to keep rotors from initiating at startup, turn on throttle hold and normal flight mode before connecting the flight battery.
- Attach hook material to the helicopter frame and loop material to the battery.
- Install the flight battery on the helicopter frame. Secure the flight battery with a hook and loop strap. Connect the battery cable to the ESC.

CAUTION: Make sure the flight battery, wire and connector does not come into contact with the motor. Failure to do so will cause the motor, ESC and battery to overheat, resulting in a crash causing property damage and injury.

- The swashplate will center, indicating that the unit is ready. The flight controller status LED will display a slow green flash once initialization has been completed.
- 8. The helicopter motor will emit a series of tones, indicating the ESC is armed.

caution: Always disconnect the Li-Po battery from the ESC power lead when not flying to avoid over-discharging the battery. Batteries discharged below the lowest approved voltage may become damaged, resulting in loss of performance and potential fire when batteries are charged.

Transmitter and Receiver Binding

Binding is the process of programming the receiver to recognize the GUID (Globally Unique Identifier) code of a single specific transmitter. You need to 'bind' your chosen Spektrum™ DSM2®/DSMX® technology equipped aircraft transmitter to the receiver for proper operation.

Binding Procedure

- 1. Program your transmitter using the Transmitter Setup found in this manual.
- 2. Connect the flight battery to the ESC.
- Press the bind button on the remote receiver to initiate binding. The orange LED on the receiver will begin flashing rapidly to indicate bind mode.
- 4. Move the throttle stick to the low throttle position in normal mode.
- Follow the procedures of your specific transmitter to enter bind mode. The system will connect within a few seconds.Once connected, the orange LED on the receiver will come on solid orange.
- 6. Disconnect the flight battery.

If you encounter problems, obey binding instructions and refer to transmitter troubleshooting guide for other instructions. If needed, contact the appropriate Horizon Product Support office.

7

Throttle Hold

Throttle hold is used to prevent the motor from powering on inadvertently. For safety, turn throttle hold ON any time you need to touch the helicopter or check the direction controls.

Throttle hold is also used to turn off the motor quickly if the helicopter is out of control, in danger of crashing, or both.

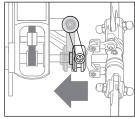
The blades will continue to spin briefly when throttle hold is activated. Pitch and direction control is still maintained.

Control Tests

CAUTION: You must complete the Tail Rotor and Cyclic tests prior to every flight. Failure to complete the tests and ensuring the sensor corrects in the proper direction can cause the helicopter to crash, resulting in property damage and injury.

Tail Rotor

- 1. Power on the transmitter.
- Turn TH HOLD ON and put transmitter in normal mode.
- 3. Connect the flight battery to the ESC.
- 4. Once initialization is complete the LED on the FC6250HX will begin flashing green.
- 5. Move the rudder stick to the right. The pitch slider on the tail shaft should move toward the tail case. If the pitch slider moves in the opposite direction, ensure the rudder channel reverse



setting within the transmitter is set to normal.

6. Release the rudder control. Manually turn the helicopter nose to the left. The flight controller should compensate by moving the tail slider towards the tail case.

Cyclic

When using a flybarless flight controller, you are controlling rotational rates while the SPMAR6250HX controls the servos. You are not directly controlling the servos with the transmitter.

It is normal for the swashplate to slowly move back to its original position after a stick input and for the servos to not move at the same speed as your control sticks.

- 1. Tilt the helicopter forward. The swashplate must tilt backward.
- 2. Roll the helicopter left. The swashplate must roll right.

Cyclic and Collective Control Test

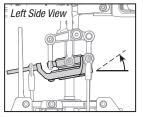
Ensure the throttle hold is ON when performing the direction control tests. Test the controls prior to each flight to ensure the servos, linkages and parts operate correctly. If the controls do not react as shown in the illustrations below, confirm the transmitter is programmed correctly before continuing on to the Motor test.

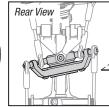


Aileron



Aileron left



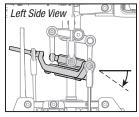


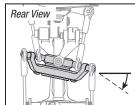


Elevator down



Aileron right

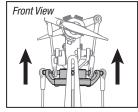




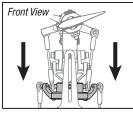


Collective Pitch









Motor Test

Place the helicopter outdoors on a clean, flat and level surface (concrete or asphalt) free of obstructions. Always stay clear of moving rotor blades.

 Before you continue, confirm that TH HOLD is ON. The motor will emit a series of tones after the helicopter's ESC has armed properly.



WARNING: The motor will spin when the throttle is increased while TH HOLD is OFF.

WARNING: Stay at least 30 feet (10 meters) away from the helicopter when the motor is running. Do not attempt to fly the helicopter at this time.

2. Ensure the throttle is lowered completely. Confirm the transmitter is still set to normal flight mode. Turn throttle hold OFF to enable throttle control. Slowly increase the throttle until the blades begin to spin. The main blades spin clockwise when viewing the helicopter from the top. The tail rotor blades spin counterclockwise when viewing the helicopter from the right-hand side.

Panic Recovery

If you get into distress while flying in any mode, activate the panic function and move the control sticks to their neutral position. SAFE technology will immediately return the aircraft to an upright level attitude, if the aircraft is at a sufficient height with no obstacles in its path. Return the collective stick to 50% and deactivate the Panic Recovery Function to return to the current flight mode.

NOTICE: Before deactivating Panic Recovery , make sure the collective stick has been returned to the 50% position. Once the Panic Recovery has been deactivated, full negative collective becomes available, which could cause the Fusion 360 SMART to descend rapidly.

- This mode is intended to provide the pilot with the confidence to continue to improve their flight skills.
- Move the collective stick to 50% and return all other transmitter controls to neutral for the quickest recovery.
- Once the model has reached a level upright attitude, the negative collective is reduced to prevent the user from pushing the model into the ground.

Pre-Flight Checklist

- ☐ Check all screws and ensure that they are tight
- Check belt tension and ensure that it is not too tight or too loose
- ☐ Check main and tail blades to ensure they are not damaged
- Check all links and make sure they move freely but do not pop off easily
- Check that the transmitter and flight batteries are fully charged
- Check all wires to ensure that they are not cut, pinched, or chaffed and are properly secured
- □ Check all wire connections
- ☐ Check gears and make sure no teeth are missing
- ☐ Make sure flight battery is properly secured
- ☐ Make sure the receiver is properly secured
- ☐ Perform a complete control test

9

- $\hfill \square$ Verify the flight controller is correcting in the proper directions
- ☐ Check that servos are functioning properly

Flying the Blade Fusion 360 SMART

Consult local laws and ordinances before choosing a location to fly your aircraft.

Select a large, open area away from people and objects. Your first flights should be outdoors in low-wind conditions. Always stay at least 30 feet (10 meters) away from the helicopter when it is flying.

The Blade Fusion 360 SMART is intended to be flown outdoors by experienced pilots.

Takeoff

Deliberately increase throttle and establish a hover at least 24" (0.6 meter) high, outside of ground effect.

CAUTION: Making large inputs to the roll or pitch controls while the helicopter is on the ground may result in a crash.

Flying

The helicopter lifts off the ground when the rotor head reaches a suitable speed. Establish a low-level hover to verify proper operation of your helicopter.

First flights should be performed in normal mode and low cyclic and rudder dual rates until you are familiar with the flying manner of the Blade Fusion 360.

CAUTION: Always fly the helicopter with your back to the sun and the wind to prevent loss of flight control.

Landing

Establish a low level hover. Deliberately lower the throttle until the helicopter lands.

When the helicopter is in stunt mode:

- The rotor head speed is constant.
- The main rotor will increase negative pitch as the throttle/collective stick is moved from the middle stick position to the low stick position. Negative pitch allows the helicopter to fly upside down and perform aerobatics.

Change between stunt and idle up modes in a hover with the throttle near the hovering stick position.

WARNING: Do not use wooden main blades with the Blade Fusion 360. Injury and/or property damage could occur. Only use Blade Fusion 360 replacement carbon fiber main blades.

Gyro Gain Adjustment

If the tail wags or oscillates, lower the gain on the gyro.
 In the transmitter gyro menu, decrease the gyro gain values a small amount at a time until the helicopter is stable within a particular flight mode.

If the tail is drifting while hovering, increase the gain on the gyro.
 In the transmitter gyro menu, increase the gyro gain values a small amount at a time until the tail starts to wag/oscillate. Afterwards, reduce the gain until the tail stops wagging/oscillating within a particular flight mode.

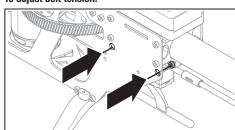
Tail Belt Tension

Belt tension that is too tight results in loss of power and causes the belt to wear more quickly. Tension that is too loose can cause belt damage and loss of tail rotor control in flight.

To check for proper belt tension:

- View the tail rotor drive belt through the opening at the back of the main frame.
- 2. Use a hex wrench or standard screwdriver to compress the belt through the opening.
- Apply light pressure on the belt, compressing the belt toward the left side of the tail boom.
- The belt tension is correct if the compressed side of the belt reaches approximately halfway to the opposite side of the belt.
 - a. If the compressed side of the belt reaches farther than halfway to the other side of the belt, the tension is too loose.
 - b. If the compressed side of the belt does not reach halfway to the other side of the belt, the tension is too tight.

To adjust belt tension:



- 1. Loosen the two screws at the back of the main frame.
- 2. Slide the boom forward or aft to adjust the belt tension.
- 3. When the belt tension is properly adjusted, tighten the two screws at the back of the frame.

ΕN

Post-Flight Inspections and Maintenance

| Ball Links | Make sure the plastic ball link holds the control ball, but is not tight (binding) on the ball. When a link is too loose on the ball, it can separate from the ball during flight and cause a crash. Replace worn ball links before they fail. |
|-------------------|--|
| Cleaning | Make sure the battery is not connected before cleaning. Remove dust and debris with a soft brush or a dry lint free cloth. |
| Bearings | Replace bearings when they become damaged. |
| Wiring | Make sure wiring does not block moving parts. Replace damaged wiring and loose connectors. |
| Fasteners | Make sure there are no loose screws, other fasteners or connectors. Do not over tighten metal screws in plastic parts. Tighten screw so parts are mated together, then turn screw only 1/8th of a turn more. |
| Rotors | Make sure there is no damage to rotor blades and other parts which move at high speed. Damage to these parts includes cracks, burrs, chips or scratches. Replace damaged parts before flying. |
| Flight Controller | Make sure the flight controller is securely attached to the frame. Replace the double-sided tape when necessary. The helicopter will crash if the flight controller separates from the helicopter frame. |

Advanced Tuning (Forward Programming)

Applies to forward programming capable Spektrum Transmitters including DX6G2, DX7G2, DX6e, DX8e, DX8G2, DX9, DX18, DX20, NX6, NX8, NX10, iX12, iX20

The Fusion 360 default settings are appropriate for most users. We recommend flying with the default parameters before making any adjustments.

The Fusion 360 BNF flight controller may be programmed from any compatible Spektrum transmitter (visit SpektrumRC. com for more information).

The flight controller shipped with BNF models has a range of adjustable parameters suitable for the Fusion 360 helicopter and is not intended for use in other aircraft.

It is important to use the included servos with the BNF flight controller because the adjustable parameters available for the SPMFC6250HX are designed around the recommended servos. It is possible there may not be enough range for the helicopter to be tuned when using alternative servos.

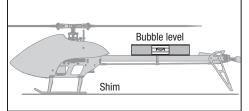
Entering the Advanced Parameters Menu

With the helicopter bound to the transmitter and powered on, enter the Function List and select Forward Programming. The list of adjustable parameters and the range of values available for tuning have been tailored for this helicopter. Make small changes to one parameter at a time and test fly the changes before changing the parameter further or changing a different parameter.

Calibration Procedure

If the helicopter is experiencing drift issues, perform the following calibration. The calibration procedure may also be needed following crash repairs.

- 1. Ensure the surface used for calibration is level.
- 2. Power on the transmitter and activate throttle hold.
- 3. Connect the flight batter to the ESC and allowing the model to initialize.
- 4. Turn Throttle Hold ON.
- Using a bubble level as shown below, level the helicopter by placing a shim under the landing skid.



- 6. Enter the Function List on your transmitter.
- 7. Select Forward Programming.
- 8. Select System Setup.
- 9. Select Calibration.
- 10. Select Apply and the calibration will begin. The LED will flash yellow indicating the calibration is proceeding normally. If the LED changes to red this indicates the model is not near level or the model was moved, in this case the calibration starts over.
- 11. After the calibration is successfully completed, the receiver LED will will change to a slow green flash which indicates the calibration has completed.
- 12. Proceed to the pre-flight check list procedure before flying your model.

Factory Reset

If the process of tuning the Fusion 360 helicopter results in undesirable flight performance, you can reset the settings back to factory defaults by selecting the Factory Reset option in Forward Programming.

- 1. Enter the Function List
- 2. Select Forward Programming
- 3. Select System Setup
- 4. Select Factory Reset
- 5. Select Apply

- 6. Perform the Setup->Swashplate->Sub Trim function and ensure the servos are properly trimmed.
- 7. Proceed with the pre-flight check list procedure before flying the model.

Advanced Tuning (Non-Forward Programming)

Applies to Spektrum transmitters not capable of forward programing including DX6i, DX7s DX8

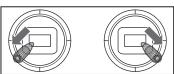
Your Blade Fusion 360 was setup at the factory and test flown. The servo adjustment steps are usually only necessary in special circumstances, such as after a crash or if a servo or linkage is replaced.

For pilots flying with a transmitter not capable of forward programming use the following procedures to make servo adjustments and perform the calibration procedure.

The advanced tuning options must be entered within 30 seconds after initialization completes. In addition the combination of dual rates and travel adjustments must result in a throw greater than 65% in order to enter the tuning modes.

Entering Servo Adjustment Mode

- 1. Lower the throttle stick to the lowest position.
- 2. Power ON the transmitter and activate throttle hold.
- 3. Install the flight battery on the helicopter frame, securing it with the hook and loop strap.
- 4. Connect the battery connector to the ESC.
- After initialization is complete (indicated by a slow green flash), hold the left stick to the bottom left corner and the right stick to the bottom right corner as shown.
- Servo Adjustment Mode is indicated by the swashplate servos jumping and then slowly moving back to center.



7. Release the sticks and proceed to the next step.

Adjusting the Servo Neutral Position

With the model in Servo Adjustment Mode, the control stick and gyro inputs are disabled and the servos are held in the neutral position. Check the position of the servo arms to verify they are perpendicular to the servos.

- If the arms are perpendicular to the servos, no adjustment is necessary.
 Exit Servo Adjustment Mode.
- If one or more servo arm is not perpendicular to the servos, continue the servo adjustment process.

While watching the swashplate servos, apply fore or aft cyclic and release. One of the servos will jump, indicating the selected servo. Apply fore or aft cyclic and release until the servo that needs to be adjusted is selected.

Once the servo you wish to adjust is selected, move the cyclic stick left or right to adjust the servo neutral position in the desired direction.

To reset the current servo to the default neutral position, hold the rudder stick full right for two seconds.

The range of adjustment is limited. If you are unable to adjust the servo arm to be perpendicular to the servo, you must reset the servo to the default neutral position, remove the servo arm and place it back onto the servo as close to perpendicular as possible. You may then adjust the servo neutral position using left or right cyclic stick.

Swashplate Leveling

Before saving your adjustments and exiting servo adjustment mode, verify the swashplate is level and both main rotor blades are at 0 degrees pitch.

If they are not, make linkage adjustments as necessary.

Saving the Servo Adjustments

- Lower the throttle stick to the lowest position and release the sticks.
- Move the tail rotor stick to the left and hold for four seconds to exit Servo Adjustment Mode. The servos will jump indicating a return to normal operation.
- 3. Release the tail rotor stick.
- 4. Perform the pre-flight checklist procedure before flying your model.

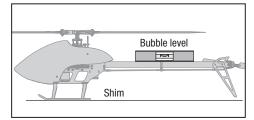
| Control Input in Servo Adjustment Mode | Action in Servo Adjustment Mode |
|---|---|
| Fore/Aft Cyclic | Select Previous or Next Servo |
| Right/Left Cyclic | Increase or Decrease Sub Trim Adjustment |
| Right Tailrotor | Hold For Two Seconds; Neutral Position is Reset on Selected Servo |
| Left Tailrotor and Low throttle | Hold for Four Seconds; Exit Servo Adjustment mode |

Calibration Procedure (Non-Forward Programming)

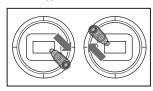
If the helicopter is experiencing drift issues after completing the trim flight procedure, perform the following calibration. The calibration procedure may also be needed following crash repairs.

To perform the calibration procedure:

- 1. Ensure the surface used for calibration is level.
- Power on the transmitter and helicopter, allowing them to initialize.
- 3. Turn Throttle Hold ON.
- 4. Ensure the main motor is disconnected.
- Using a bubble level as shown below, level the helicopter by placing a shim under the landing skid.



6. Hold the left stick to the bottom right corner, and the right stick to the upper left corner.



7. The LED on the Flight Controller will flash yellow while caibrating

Do not move the helicopter until the calibration is completed. If the LED displays a red LED an error has occurred. Begin the calibration procedure again, starting with step 1.

After the calibration is successfully completed, the receiver LED will blink green.

| LED Indicator on FC | Indicator Description |
|-------------------------|--|
| Red Solid | FC6250HX waiting for receiver connection, system will not initialize until connected |
| Yellow Flash | Calibrating |
| Slow Green Flash | Ready to Fly |
| Red and Yellow Flash | Failsafe Active |

Flight Mode and Rate Selection

In Stability Mode the bank angle is limited. When the cyclic stick is released the model will return to level.

In Intermediate Mode the bank angle is not limited. When the cyclic stick is released the model will not return to level. This mode is great for learning forward flight and basic aerobatics such as stall turns and loops.

In Agility Mode the bank angle is not limited. When the cyclic stick is released the model will not return to level. This mode is great for 3D aerobatics such as stationary flips and tic tocs.

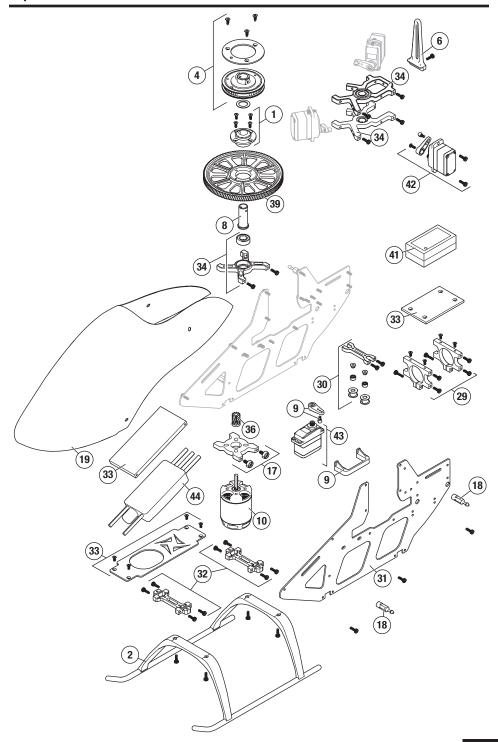
Change rates in any mode by moving the two-position dual rate switch.

- Low rate reduces the control rates, providing an easier to fly model. Beginners should use low rate for initial flights.
- High rate provides full control and should be used by intermediate and experience pilots.

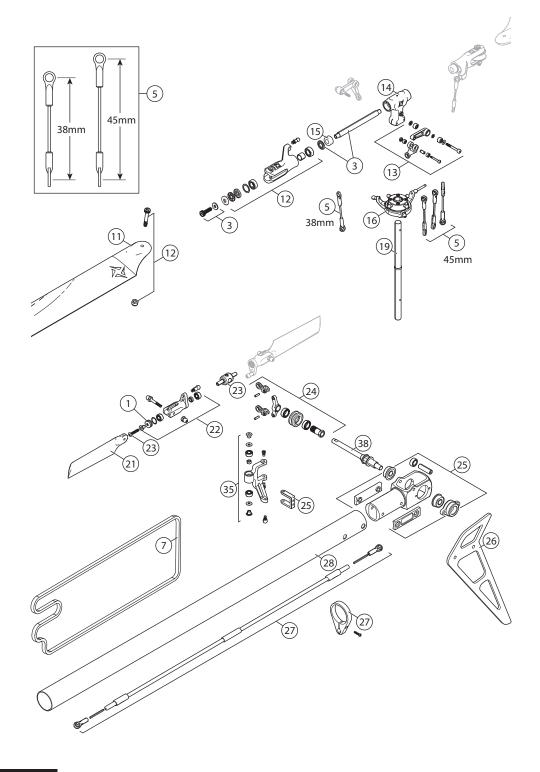
Troubleshooting Guide

| Problem | Possible Cause | Solution |
|--|---|---|
| | Low flight battery or transmitter battery voltage | Fully charge or replace the flight battery and/or transmitter batteries |
| Helicopter will not bind to the transmitter | Transmitter is not in bind mode | Power on the transmitter while holding the Trainer/Bind switch. Hold the Trainer/Bind switch until binding is complete |
| (during binding) | Transmitter too close to the helicopter during binding process | Power off the transmitter. Move the transmitter further away from the helicopter. Disconnect and reconnect the flight battery to the helicopter and follow binding instructions |
| Helicopter will not link to the transmitter | Helicopter is bound to a different model memory (ModelMatch™ radios only) | Disconnect the flight battery. Select the correct model memory on the transmitter. Reconnect the flight battery |
| (after binding) | Flight battery/Transmitter battery charge is too low | Replace or recharge batteries |
| Flight controller will not | The helicopter was moved during initialization | Lay the helicopter on its side during initialization if windy |
| initialize | The transmitter is powered off | Power on the transmitter |
| | Controls are not centered | Center elevator, aileron and rudder controls. Make sure the throttle is at idle |
| | Throttle not at idle and/or throttle trim is too high | Lower the throttle stick and lower the throttle trim |
| Helicopter will not respond | The transmitter is not in normal mode or throttle hold is on | Make sure the transmitter is in normal mode and throttle hold is off |
| to the throttle but responds to other controls | The motor is not connected to the ESC or the motor wires are damaged | Connect the motor wires to the ESC and check motor wires for damage |
| | Flight battery charge is too low | Replace or recharge flight battery |
| | Throttle channel is reversed | Reverse the throttle channel on the transmitter |
| | Flight battery has low voltage | Fully charge the flight battery |
| | Flight battery is old or damaged | Replace the flight battery |
| Helicopter power is lacking | Flight battery cells are unbalanced | Fully charge the flight battery, allowing the charger time to balance the cells |
| | Excessive current is being drawn through the BEC | Check all servos and the helicopter motor for damage |
| | Tail drive belt tension is not correct | See "Tail Belt Tension" section in this manual |
| | Main rotor head is not spinning in the correct direction | Make sure the main rotor head is spinning clockwise. Refer to the motor control test |
| Helicopter will not lift off | Transmitter settings are not correct | Check throttle and pitch curve settings and pitch control direction |
| Thericopter will flot lift on | Flight battery has low voltage | Fully charge the flight battery |
| | Main rotor blades are installed backwards | Install the main rotor blades with the thicker side as the leading edge |
| The helicopter tail spins out of control | Rudder control and/or sensor direction reversed | Make sure the rudder control and the rudder sensor are operating in the correct direction |
| | Tail servo is damaged | Check the rudder servo for damage and replace if necessary |
| | Inadequate control arm throw | Check the rudder control arm for adequate travel and adjust if necessary |
| | Tail belt is too loose | Make sure the tail drive belt tension is adjusted correctly |
| T | Cyclic gain is too high | Tuning options using forward programming are available under the "Advanced Settings" section in this manual |
| The helicopter wobbles in flight | Headspeed is too low | Increase the helicopter's head speed via your transmitter settings and/or using a freshly charged flight pack |
| | Dampers are worn | Replace the main rotor head dampers |

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Parts List

| # | Part # | Description |
|----|---------|-----------------------------------|
| 1 | BLH1620 | 3x8x3.5 Thrust Bearing (2) |
| 2 | BLH1645 | Landing Gear Set: B450 |
| 3 | BLH4705 | Spindle Set (2): 360 CFX |
| 4 | BLH4710 | Belt Drive Puller: 360 CFX |
| 5 | BLH4720 | Linkage Set: 360 CFX |
| 6 | BLH4721 | Anti-Rotation Bracket: 360 CFX |
| 7 | BLH4728 | Tail Drive Belt: 360 CFX |
| 8 | BLH4735 | one way brng shaft Blade 360 CF |
| 9 | BLH4831 | Srvo arm/link ball:270 CFX FS270 |
| 10 | BLH5051 | Brushless Out-Runner Motor 3400Kv |
| 11 | BLH5201 | Fusion 350mm Main Blade |
| 12 | BLH5202 | Main Grip Set (2): Fusion 360 |
| 13 | BLH5203 | Washout Mixing Arms: Fusion 360 |
| 14 | BLH5204 | Main Rotor Headblock: Fusion 36 |
| 15 | BLH5205 | Damper Set (2) 90 : Fusion 360 |
| 16 | BLH5206 | Swashplate: Fusion 360 |
| 17 | BLH5207 | Motor Mount: Fusion 360 |
| 18 | BLH5208 | Body Post Mounts (4): Fusion 36 |
| 19 | BLH5209 | Fusion 360 Painted Canopy |
| 20 | BLH5210 | Main Shaft: Fusion 360 |
| 21 | BLH5211 | Fusion 65mm Tail Blade Set |
| 22 | BLH5212 | AL Tail Grip Set: Fusion 360 |

| # | Part # | Description |
|----|-------------|------------------------------------|
| 23 | BLH5213 | Tail Rotor Hub: Fusion 360 |
| 24 | BLH5214 | Tail Pitch Slider: Fusion 360 |
| 25 | BLH5215 | Rear Tail Case: Fusion 360 |
| 26 | BLH5216 | Vertical Tail Fin: Fusion 360 |
| 27 | BLH5217 | Tail Rotor Pushrod: Fusion 360 |
| 28 | BLH5218 | Tail Boom Set (2): Fusion 360 |
| 29 | BLH5219 | Tail Boom Clamp (2): Fusion 360 |
| 30 | BLH5220 | Tail Belt Guide: Fusion 360 |
| 31 | BLH5221 | Frame (1): Fusion 360 |
| 32 | BLH5222 | Gear Mount (2): Fusion 360 |
| 33 | BLH5224 | Carbon Plates: Fusion 360 |
| 34 | BLH5225 | Bear Block Set (3): Fusion 360 |
| 35 | BLH5226 | Tail Rotor Bellcrank: Fusion 360 |
| 36 | BLH5231 | 11T Helical Steel Pinion |
| 37 | BLH5233 | Plastic Tail Case: Fusion 360 |
| 38 | BLH5336 | Tailshaft CNC Fusion 270 |
| 39 | BLH5337 | Helical Main Gear, 135T |
| 40 | SPM4651T | SRXL2 Serial Telemetry Receiver |
| 41 | SPMFC6250HX | FC6250HX Helicopter FBL System |
| 42 | SPMSH3055 | H3055 M-T / U-S MicroCyclicServ |
| 43 | SPMSH3065 | H3065 M-T / U-S Micro Tail Serv |
| 44 | SPMXAE1045 | Avian 45Amp Brushless Smart ESC 6S |

Recommended Parts List

| Part # | Description |
|--------------|---------------------------------|
| SPMX22003S50 | 2200mAh 3S 11.1V Smart 50C; IC3 |

Optional Parts List

| Part # | Description |
|-----------|-----------------|
| SPMSP1040 | Gear Set: H3050 |
| SPMSP1041 | Gear Set: H3060 |

| Part # | Description |
|-----------|------------------------|
| SPMSP2052 | Case Set: H3050, H3060 |
| | |

Limited Warranty

What this Warranty Covers

Horizon Hobby, LLC, (Horizon) warrants to the original purchaser that the product purchased (the "Product") will be free from defects in materials and workmanship at the date of purchase.

What is Not Covered

This warranty is not transferable and does not cover (i) cosmetic damage, (ii) damage due to acts of God, accident, misuse, abuse, negligence, commercial use, or due to improper use, installation, operation or maintenance, (iii) modification of or to any part of the Product, (iv) attempted service by anyone other than a Horizon Hobby authorized service center, (v) Product not purchased from an authorized Horizon dealer, (vi) Product not compliant with applicable technical regulations, or (vii) use that violates any applicable laws, rules, or regulations.

OTHER THAN THE EXPRESS WARRANTY ABOVE, HORIZON MAKES NO OTHER WARRANTY OR REPRESENTATION, AND HEREBY DISCLAIMS ANY AND ALL IMPLIED WARRANTIES, INCLUDING, WITHOUT LIMITATION, THE IMPLIED WARRANTIES OF NON-INFRINGEMENT, MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. THE PURCHASER ACKNOWLEDGES THAT THEY ALONE HAVE DETERMINED THAT THE PRODUCT WILL SUITABLY MEET THE REQUIREMENTS OF THE PURCHASER'S INTENDED USE.

Purchaser's Remedy

Horizon's sole obligation and purchaser's sole and exclusive remedy shall be that Horizon will, at its option, either (i) service, or (ii) replace, any Product determined by Horizon to be defective. Horizon reserves the right to inspect any and all Product(s) involved in a warranty claim. Service or replacement decisions are at the sole discretion of Horizon. Proof of purchase is required for all warranty claims. SERVICE OR REPLACEMENT AS PROVIDED UNDER THIS WARRANTY IS THE PURCHASER'S SOLE AND EXCLUSIVE REMEDY.

Limitation of Liability

HORIZON SHALL NOT BE LIABLE FOR SPECIAL, INDIRECT, INCIDENTAL OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR PRODUCTION OR COMMERCIAL LOSS IN ANY WAY. REGARDLESS OF WHETHER SUCH CLAIM IS BASED IN CONTRACT. WARRANTY TORT, NEGLIGENCE, STRICT LIABILITY OR ANY OTHER THEORY OF LIABILITY. EVEN IF HORIZON HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. Further, in no event shall the liability of Horizon exceed the individual price of the Product on which liability is asserted. As Horizon has no control over use, setup, final assembly, modification or misuse, no liability shall be assumed nor accepted for any resulting damage or injury. By the act of use, setup or assembly, the user accepts all resulting liability. If you as the purchaser or user are not prepared to accept the liability associated with the use of the Product, purchaser is advised to return the Product immediately in new and unused condition to the place of purchase.

Law

These terms are governed by Illinois law (without regard to conflict of law principals). This warranty gives you specific legal rights, and you may also have other rights which vary from state to state. Horizon reserves the right to change or modify this warranty at any time without notice.

WARRANTY SERVICES

Questions, Assistance, and Services

Your local hobby store and/or place of purchase cannot provide warranty support or service. Once assembly, setup or use of the Product has been started, you must contact your local distributor or Horizon directly. This will enable Horizon to better answer your

questions and service you in the event that you may need any assistance. For questions or assistance, please visit our website at www.horizonhobby.com, submit a Product Support Inquiry, or call the toll free telephone number referenced in the Warranty and Service Contact Information section to speak with a Product Support representative.

Inspection or Services

If this Product needs to be inspected or serviced and is compliant in the country you live and use the Product in, please use the Horizon Online Service Request submission process found on our website or call Horizon to obtain a Return Merchandise Authorization (RMA) number. Pack the Product securely using a shipping carton. Please note that original boxes may be included, but are not designed to withstand the rigors of shipping without additional protection. Ship via a carrier that provides tracking and insurance for lost or damaged parcels. as Horizon is not responsible for merchandise until it arrives and is accepted at our facility. An Online Service Request is available at http:// www.horizonhobby.com/content/service-center_render-service-center. If you do not have internet access, please contact Horizon Product Support to obtain a RMA number along with instructions for submitting your product for service. When calling Horizon, you will be asked to provide your complete name, street address, email address and phone number where you can be reached during business hours. When sending product into Horizon, please include your RMA number, a list of the included items, and a brief summary of the problem. A copy of your original sales receipt must be included for warranty consideration. Be sure your name, address, and RMA number are clearly written on the outside of the shipping carton.

NOTICE: Do not ship LiPo batteries to Horizon. If you have any issue with a LiPo battery, please contact the appropriate Horizon Product Support office.

Warranty Requirements

For Warranty consideration, you must include your original sales receipt verifying the proof-of-purchase

date. Provided warranty conditions have been met, your Product will be serviced or replaced free of charge. Service or replacement decisions are at the sole discretion of Horizon.

Non-Warranty Service

Should your service not be covered by warranty, service will be completed and payment will be required without notification or estimate of the expense unless the expense exceeds 50% of the retail purchase cost. By submitting the item for service you are agreeing to payment of the service without notification. Service estimates are available upon request. You must include this request with your item submitted for service. Non-warranty service estimates will be billed a minimum of ½ hour of labor. In addition you will be billed for return freight. Horizon accepts money orders and cashier's checks, as well as Visa, MasterCard, American Express, and Discover cards. By submitting any item to Horizon for service, you are agreeing to Horizon's Terms and Conditions found on our website http://www.horizonhobby.com/content/service-center.

ATTENTION: Horizon service is limited to Product compliant in the country of use and ownership. If received, a non-compliant Product will not be serviced. Further, the sender will be responsible for arranging return shipment of the un-serviced Product, through a carrier of the sender's choice and at the sender's expense. Horizon will hold non-compliant Product for a period of 60 days from notification, after which it will be discarded.

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Warranty and Service Contact Information

| Country of Purchase | Horizon Hobby | Contact Information | Address |
|--------------------------|---|--|--|
| United States of America | Horizon Service Center (Repairs and Repair Requests) | servicecenter.horizonhobby.com/RequestForm/ | 2904 Research Rd Champaign, Illinois, 61822 USA |
| | Horizon Product Support (Product Technical Assistance) | productsupport@horizonhobby.com 877-504-0233 | |
| | Sales | websales@horizonhobby.com 800-338-4639 | |
| European Union | Horizon Technischer Service Sales: Horizon Hobby GmbH | service@horizonhobby.de +49 (0) 4121 2655 100 | Hanskampring 9 D 22885 Barsbüttel, Germany |

FCC Information

FCC ID: BRWOSTLMRX2

This equipment complies with FCC and IC radiation exposure limits set forth for an uncontrolled environment. This equipment should be installed and operated with minimum distance 20cm between the radiator and/or antenna and your body (excluding fingers, hands, wrists, ankles and feet). This transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.

Supplier's Declaration of Conformity Blade Fusion 360 SMART BNF (BLH6150)

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful

interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

CAUTION: Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are

designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- · Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.
 Horizon Hobby, LLC

2904 Research Rd., Champaign, IL 61822

Email: compliance@horizonhobby.com

Web: HorizonHobby.com

IC Information

CAN ICES-3 (B)/NMB-3(B) IC: 6157A-QSTMRX2

This device contains license-exempt transmitter(s)/ receivers(s) that comply with Innovation, Science, and Economic Development Canada's license-exempt RSS(s). Operation is subject to the following 2 conditions:

- 1. This device may not cause interference.
- This device must accept any interference, including interference that may cause undesired operation of the device.

Compliance Information for the European Union



EU Compliance Statement: Blade Fusion 360 SMART BNF (BLH6150); Hereby, Horizon Hobby, LLC declares

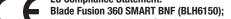
that the device is in compliance with the

following: EU Radio Equipment Directive 2014/53/EU; RoHS 2 Directive 2011/65/EU; RoHS 3 Directive - Amending 2011/65/EU Annex II 2015/863.

The full text of the EU declaration of conformity is available at the following internet address: https://www. horizonhobby.com/content/support-render-compliance.

Wireless Frequency Range and Wireless Output Power: Receiver

2402-2478 MHz 18.87dBm



EU Manufacturer of Record:

Horizon Hobby, LLC 2904 Research Road Champaign, IL 61822 USA

EU Importer of Record:

Horizon Hobby, GmbH Hanskampring 9 22885 Barsbüttel Germany

WEEE NOTICE:



This appliance is labeled in accordance with European Directive 2012/19/EU concerning waste of electrical and electronic equipment (WEEE). This label indicates that this product should not be disposed of with household waste. It should be deposited at an

appropriate facility to enable recovery and recycling.



20



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Created 12/20

BLH6150

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